

# Containers

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# Kinds of Standard Containers

- Array
- Dynamic Array
- Linked List
- Stack
- Queue
- Priority Queue
- Tree
- Binary Search Tree
- Dictionary (map)
- Set
- Graph
- Directed Acyclic Graph

# Container Algorithms

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- Insert
- Remove
- Iterate
- Random Access
- Find
- Sort

# Iterators

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- The benefits of using iterators:
  - Don't break the class encapsulation
  - Simple to use, even for complex containers  
(make them feel more like arrays)

# Algorithmic Complexity

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- The time spent on running the algorithm may be a function of the number of elements in the container:  $T = f(n)$
- Enough to consider an approximation for  $f(n)$  that gives us the „on the order of“ complexity
  - $O(1)$  – Not dependent on  $n$
  - $O(n)$  – Loops over elements
  - $O(n^2)$  – Nested loops
  - $O(\log n)$  – Eliminate  $\frac{1}{2}$  of elements every step

Pick a container that provides the best of these for the algorithm you will use the most commonly

# Container Characteristics

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- What is the memory overhead required?
  - E.g. pointers that need to be stored
- Is the data stored contiguously in memory?
  - This has great impact on cache performance

# Build Your Own?

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- STL

- + Robust, rich, included

- Slower (generic), memory hog, dynamic allocation, not same on all compilers (use STLPort)

- Use when memory is not at premium

- Boost

- + Works around STL problems, solves complex problems (e.g. smart pointers), well documented

- Huge Lib files, not guaranteed code, lack of backward compatibility, particular license

# Build Your Own? (cont.)

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- Loki
  - + Tricks compilers to do things they were not designed to do through „template metaprogramming“
  - Hard to understand



# Dynamic Arrays

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- Fixed size c-style arrays are good!
  - No new memory allocation
  - Contiguous memory (good for caching)
- Dynamic arrays sometimes needed
  - Buffer can be grown as needed (by n or by doubling)
  - Actually new buffer allocated, then data copied
  - This is costly!
  - Maybe use this at development time and then change to fixed size when we know the biggest size

# Linked Lists

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- **Extrusive List**
  - Link structure is separate from the elements
  - + Elements can be in many lists
  - - Link objects dynamically allocated
- **Intrusive List**
  - Link structure allocated as part of elements
  - + You get links „for free“
  - - Elements stuck in one list at a time

# Linked Lists (cont.)

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- Circular Lists store the root also as a regular link, where the Next and Prev pointers serve as the Beginning and End pointers
  - Simplifies the algorithms

# Dictionarys and Hash Tables

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- Dictionarys implemented as:
  - Binary Tree
    - Key-value pair in each node (key sorted)
    - $O(\log n)$
  - Hash Table
    - Fixed size key slot table
    - $O(1)$  in the absence of Collision

# Collisions Resolved

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- Open Table

- + Linked list at each index can grow indefinitely
- Dynamic memory allocation

- Closed Table

- Use Probing for empty slots (while they exist)
- + Fixed amount of memory (good on consoles!)
- Upper limit

# Hashing

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Hash value:  $h = H(k)$

Table index:  $i = h \bmod N$

Hash function  $H$ :

- is crucial for distributing the keys well
- has to be quick
- has to be deterministic

# Probing

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- Different ways
  - Linear
  - Quadratic (to avoid clustering of keys)