



T-622-ARTI, Introduction to Artificial Intelligence  
Spring 2011

## Problem Set 2

Worth 5% of final course grade

Due by 23:59 on Thursday the 17th of March

Group Size 1-2

**Student Name:** \_\_\_\_\_

### 1. (30%) Inference with Propositional Logic

You are an unmanned space ship sent to explore one of Jupiter's moons, Europa. Your precious **Knowledge Base** contains the following **sentences**:

- [A]  $\text{ChemoSynth} \Rightarrow \text{LifeEnergy}$
- [B]  $\neg \text{HighTemp} \wedge \text{TidalFlexing} \Rightarrow \text{Radiation}$
- [C]  $\text{Oxygen} \wedge \neg \text{HydroThermal} \Rightarrow \text{LifeSafe}$
- [D]  $\text{HighTemp} \vee \neg \text{TidalFlexing} \Rightarrow \neg \text{LifeSafe}$
- [E]  $\text{HydroThermal} \wedge \text{LifeEnergy} \Rightarrow \text{Life}$

Once you arrive on Europa your sensors tell you the following:

- [F]  $\neg \text{Radiation}$
- [G]  $\text{Oxygen}$
- [H]  $\text{ChemoSynth}$

**Use inference** to determine whether there is life on Europa or not. You may use the rules and equivalences shown on the formula page (at the back). Each time you add a new sentence to your Knowledge Base, indicate what sentences, equivalences and/or rules you are using (*note*: number of lines below does not indicate length of solution).

[I] \_\_\_\_\_ from \_\_\_\_\_

[J] \_\_\_\_\_ from \_\_\_\_\_

[K] \_\_\_\_\_ from \_\_\_\_\_

[L] \_\_\_\_\_ from \_\_\_\_\_

[M] \_\_\_\_\_ from \_\_\_\_\_

[N] \_\_\_\_\_ from \_\_\_\_\_

[O] \_\_\_\_\_ from \_\_\_\_\_

[P] \_\_\_\_\_ from \_\_\_\_\_

[Q] \_\_\_\_\_ from \_\_\_\_\_

[R] \_\_\_\_\_ from \_\_\_\_\_

[S] \_\_\_\_\_ from \_\_\_\_\_

## 2. (20%) First Order Logic

Using at least the symbols  $\text{Contains}(x,y)$  and  $\text{Good}(x)$  write the **first order logic** statements that express the following:

- a) Some good food contains chili powder.
  
- b) All good food contains salt but no eggplant.
  
- c) The food must be old or contain some eggplant if it is bad.

### 3. (30%) Knowledge Representation and Reasoning (with PowerLoom)

- a) Translate the following sentences (using relation predicates, functions and constants) into First Order Logic statements for **PowerLoom**:
- a. Tony, Mike and John are members of the Alpine Club.  
*HINT: you can suppose that being a "member" means being a "member of the Alpine Club";*
  - b. Every member of the Alpine Club who is not a Skier is a mountain Climber;
  - c. Mountain climbers do not like rain, and anyone who does not like snow is not a skier;
  - d. Mike dislikes whatever Tony likes, and likes whatever Tony dislikes;
  - e. Tony likes rain and snow.
- b) Is there a member of Alpine Club who is a mountain climber but not a skier? If so, who is?  
*HINT: use the retrieve command in PowerLoom to obtain this information from the Knowledge Base built so far.*
- c) **Submit your PowerLoom module file (\*.PLM) as part of this problem set** (you can zip the files together if you want).

#### 4. (20%) Planning

You are a **robot** that gets the task of securing the rooms of a building. The building has 3 rooms numbered 1 through 3. In order to secure a room you need to have the remote control that seals it shut. This remote control is currently sitting in one of the rooms. You have the following **STRIPS** operators available to you and the closed world assumption holds.

**Action**( GotoRoom(x,y) ),

**Precond:** At(robot, x)

**Add:** At(robot, y)

**Delete:** At(robot, x)

**Action** ( Pickup(o) ),

**Precond:** At(robot,x)  $\wedge$  At(o,x)

**Add:** Holding(robot,o)

**Delete:** At(o,x)

**Action** ( Drop(o) ),

**Precond:** At(robot,x)  $\wedge$  Holding(robot,o)

**Add:** At(o,x)

**Delete:** Holding(robot,o)

**Action** ( SecureRoom(x) ),

**Precond:** At(robot,x)  $\wedge$  Holding(robot,remote)

**Add:** Secure(x)

**Delete:** -

**Initial State:**

At(robot,3)  $\wedge$  At(remote,2)

**Goal State:**

At(robot,1)  $\wedge$  At(remote,1)  $\wedge$  Secure(1)  $\wedge$  Secure(2)  $\wedge$  Secure(3)

You have decided to do backward chaining to plan your course of action. **Regress the goal** through **three actions**. Show both the actions and intermediate states.

## Formula Page

### Logical Equivalence:

1.  $(a \wedge b) \equiv (b \wedge a)$
2.  $(a \vee b) \equiv (b \vee a)$
3.  $((a \wedge b) \wedge c) \equiv (a \wedge (b \wedge c))$
4.  $((a \vee b) \vee c) \equiv (a \vee (b \vee c))$
5.  $\neg(\neg a) \equiv a$
6.  $(a \Rightarrow b) \equiv (\neg b \Rightarrow \neg a)$
7.  $(a \Rightarrow b) \equiv (\neg a \vee b)$
8.  $(a \Leftrightarrow b) \equiv ((a \Rightarrow b) \wedge (b \Rightarrow a))$
9.  $\neg(a \wedge b) \equiv (\neg a \vee \neg b)$
10.  $\neg(a \vee b) \equiv (\neg a \wedge \neg b)$
11.  $(a \wedge (b \vee c)) \equiv ((a \wedge b) \vee (a \wedge c))$
12.  $(a \vee (b \wedge c)) \equiv ((a \vee b) \wedge (a \vee c))$

### Sound Inference Rules:

13. From  $\{ (a \Rightarrow b), a \}$  infer  $b$  (Modus Ponens)
14. From  $\{ (a \Rightarrow b), \neg b \}$  infer  $\neg a$  (Modus Tolens)
15. From  $\{ a, b \}$  infer  $(a \wedge b)$
16. From  $\{ (a \wedge b), . \}$  infer  $a$
17. From  $\{ (a \wedge b), . \}$  infer  $b$