

Intelligent Agents

Russell and Norvig:
Chapter 2

Agents

◆ “An **agent** is anything that can be viewed as **perceiving** its **environment** through **sensors** and acting upon that environment through **actuators**”.

What are the sensors and actuators?

Agents

◆ For example

- Humans
- Animals
- Robots
- Various software systems

Agents: Terminology

◆ Perceiving

- **Percept**: Agent's perceptual inputs at any given instant
- **Percept sequence**: Complete history of everything the agent has perceived.

Agents: Terminology

◆ Acting

- **Agent function**: decides what action to take in any given situation (possibly non-deterministic)
- In general, an agent's choice of action can depend on the *entire percept sequence* observed to date.
- **Agent program**: implements an agent function internally.

Agent Program

◆ The AI is to design the **agent program**

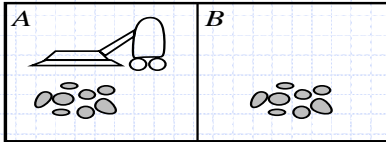
- Agent = architecture + program

◆ Easy?

- Simply fill out the agent function table!

Even though we could, impractical except for most simple problems

The Vacuum-Cleaner World



◆ Agent Function

Percept sequence

[A, Clean]

[A, Dirty]

[B, Clean]

[B, Dirty]

[A, Clean], [A, Clean]

...

Action

Right

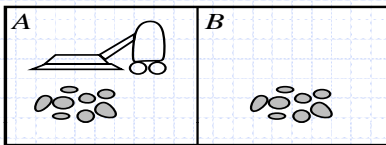
Suck

Left

Suck

Right

The Vacuum-Cleaner World



◆ Agent Program

function DECIDE([location, status]) returns an action

if status = **Dirty** then return **Suck**

else if location = **A** then return **Right**

else if location = **B** then return **Left**

The Concept of Rationality

- ◆ Rational behavior is making the “right” decisions *based on what you know*.
- ◆ What is rational at any given time depends on
 - The **performance measure** that defines the criterion of success
 - The agent's **prior knowledge** of the environment
 - The actions that the agent **can perform**
 - The agent's **percept sequence** to date.

Rational Agent

◆ “For each possible percept sequence, a **rational agent** should select an action that is **expected to maximize its performance** measure, **given the evidence** provided by the percept sequence and whatever built-in knowledge the agent has.”

◆ Note:

- Does not imply *perfect* decision making.
- Does usually imply a learning agent.

The Nature of Environments

◆ Task environment

- “Problem domain”

◆ Specifying the task environment

- Performance measure
- Environment
- Actuator
- Sensors

◆ See figures 2.4 and 2.5 for examples

The Nature of Environments

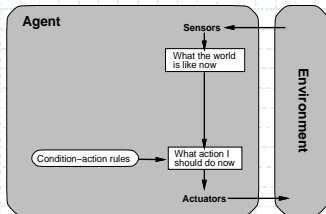
◆ Properties of environments

- Fully vs. partially observable
- Deterministic vs. Stochastic
 - Deterministic except for other agents: strategic
- Episodic vs. Sequential
- Static vs. Dynamic
- Discrete vs. Continuous
- Single vs. Multi-agent
 - Cooperative
 - Competitive

Simple Reflex Agent

◆ Simple reflex agents

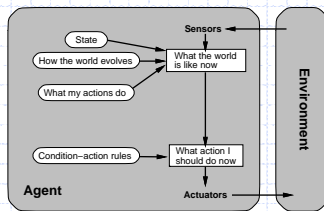
- Only current percept
- Condition-Action Rules



Model-Based Reflex Agent

◆ Model-based reflex agents

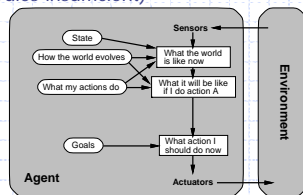
- Model of world – internal state
- World evolves
- Actions affect it



Goal-Based Agent

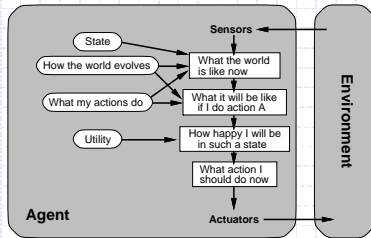
◆ Goal-based agents

- Current State and a Goal.
- Desired Future State: planning and search used.
- (condition-action rules insufficient)

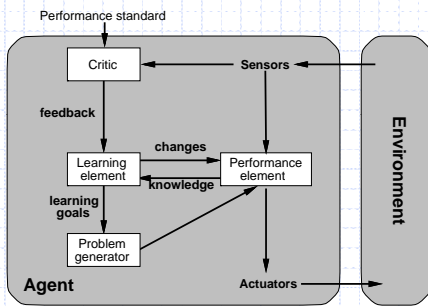


Utility Based Agent

- ◆ Utility based agents
 - Utility function returns a "happy value" about state



Learning Agents



Summary

- ◆ Agent
 - ◆ Rational Agent
 - ◆ Task environment
 - ◆ Structure of Agents
 - Simple reflex
 - Model-Based
 - Goal-Based
 - Utility-Based
 - ◆ Learning Agents
